

Set #8 – Conservation of Energy

1. A 3-kg collar can slide without friction on a vertical rod and is resting in equilibrium on a spring. It is pushed down, compressing the spring 150mm, and released. Knowing that the spring constant $k = 2.6\text{ kN/m}$, determine

- the maximum height h reached by the collar above its equilibrium position,
- the maximum velocity of the collar.

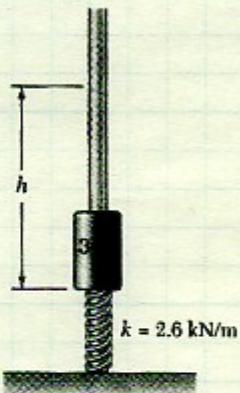
Given: $m = 3\text{ kg}$

Frictionless

resting on spring

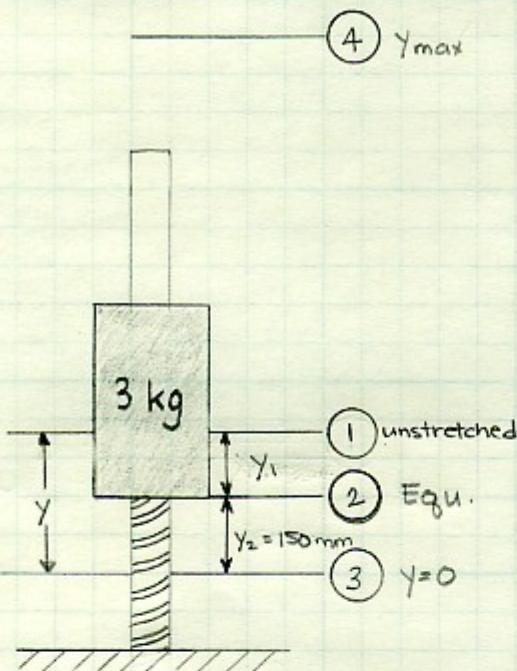
compressed 150 mm = .150 m

$$K = 2.6 \text{ kN/m} = 2600 \text{ N/m}$$



Find: (a) max. height, y_{\max} , above equilibrium position.
 (b) max. velocity, v_{\max} .

Solution:



(1) → This is the position of the unstretched spring.

(2) → Because the collar is resting on the spring, it compresses the spring to this equilibrium position.

(3) → The collar is pushed down 150 mm.

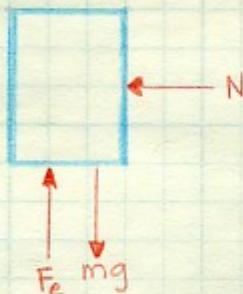
(4) → The maximum height that the collar reaches once it is released.

First, we must find the distance x . (1 to 2)

$$\begin{aligned} F &= ky, \\ mg &= ky, \rightarrow y_1 = \frac{mg}{k} \\ &= (3\text{ kg})(9.81 \text{ m/s}^2) \\ &\quad 2600 \text{ N/m} \\ &= .01132 \text{ m} \end{aligned}$$

Set #8

1. continued.



Note: This FBD only corresponds to the points in time when the collar remains in contact with the Spring.

Once the spring reaches its undeflected length, the collar leaves the spring.

$$(a_1) \quad T_3 + U_{1 \rightarrow 2} = T_4 \quad \textcircled{1}$$

$$\begin{aligned} U_{1 \rightarrow 2} &= V_{g_1} - V_{g_2} \\ U_{1 \rightarrow 2} &= V_{e_1} - V_{e_2} \end{aligned} \quad \textcircled{2}$$

Plugging $\textcircled{2}$ into $\textcircled{1}$, we obtain the following:

$$\rightarrow T_3 + V_{g_3} + V_{e_3} = T_4 + V_{g_4} + V_{e_4}$$

$$O + O + \frac{1}{2}ky^2 = O + mgy_4$$

$$\begin{aligned} y_4 &= \frac{ky^2}{2mg} \\ &= \frac{2600 (.150 + .0132)^2}{2(3)(9.81)} \\ &= 1.15 \text{ m} \end{aligned}$$

$$\text{So, } y_{\max} = 1.15 \text{ m} - .15 \text{ m}$$

$$= \underline{\underline{1.00 \text{ m}}} \text{ above equilibrium position}$$

Set #8

1. continued.

(b) v_{max} occurs at equilibrium position because

$$\frac{dv}{dt} = 0 \text{ when } a=0$$

and $a=0$ when $F_{net}=0$

$$T_3 + V_{g_3} + V_{e_3} = T_2 + V_{g_2} + V_{e_2}$$

$$0 + 0 + \frac{1}{2}k\gamma^2 = \frac{1}{2}mv_{max}^2 + mg\gamma_2 + \frac{1}{2}k\gamma_1^2$$

$$(2600)(.15 + .01132)^2 = (3)v_{max}^2 + (2)(3)(9.81)(.15) + (2600)(.01132)^2$$

$$\underline{\underline{v_{max} = 4.42 \text{ m/s}}}$$

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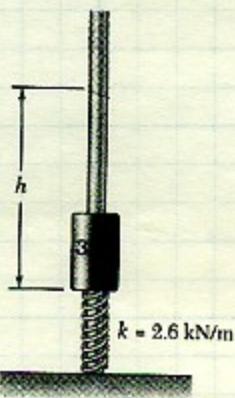
2. A 3-kg collar can slide without friction on a vertical rod and is held so that it just touches an undeformed spring. Determine the maximum deflection of the spring

- if the collar is slowly released until it reaches an equilibrium position,
- if the collar is suddenly released.

Given: $m = 3 \text{ kg}$ $k = 2.6 \text{ kN/m}$

Frictionless

Collar just touches undeformed spring.



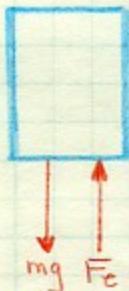
Find: Determine the maximum deflection of the spring if.

- the collar is slowly released.
- the collar is suddenly released.

Solution:

$$\begin{aligned}
 \text{(a.) } F &= kx \rightarrow x = \frac{F}{k} \\
 &= \frac{mg}{k} \\
 &= \frac{(3 \text{ kg})(9.81 \text{ m/s}^2)}{2600 \text{ N/m}} \\
 &= \underline{\underline{11.32 \text{ mm}}}
 \end{aligned}$$

(b.)



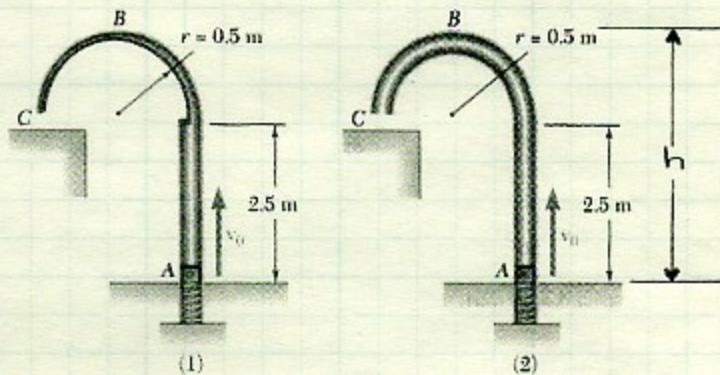
$$\begin{aligned}
 T_1 + V_{g1} + V_{e1} &= T_2 + V_{g2} + V_{e2} \\
 0 + 0 + 0 &= 0 + \frac{1}{2}ky_2^2 + mg y_2
 \end{aligned}$$

$$\begin{aligned}
 y_2 &= -\frac{2mg}{k} \\
 &= -\frac{2(3)(9.81)}{2600} \\
 &= \underline{\underline{22.6 \text{ mm}}}
 \end{aligned}$$

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3. A 200-g package is projected upward with a velocity v_0 by a spring at A; it moves around a frictionless loop and is deposited at C. For each of the two loops shown, determine

- the smallest velocity v_0 for which the package will reach C,
- the corresponding force exerted by the package on the loop just before the package leaves the loop at C.



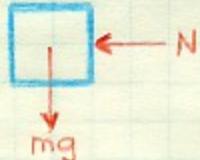
Given: $m = 200 \text{ g} = .2 \text{ kg}$
 $v_0 \uparrow$
Frictionless

Find: For each loop, determine

- v_{\min} to reach C without bottom of track
 v_{\min} to reach C with bottom.
- Force exerted on loop at C (without bottom).
Force exerted on loop at C (with bottom.)

Solution:

(a.)



To get v_0 :

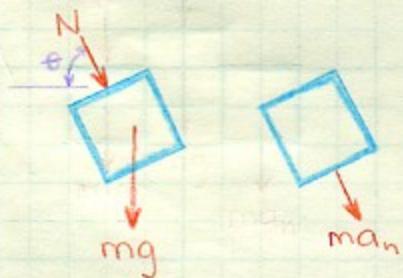
$$T_A + V_A = T_B + V_B \\ \frac{1}{2}mv_0^2 + 0 = \frac{1}{2}mv_B^2 + mgh$$

(Note: Refer to figure for h.)

$$v_0^2 = v_B^2 + 2mgh \quad \textcircled{1}$$

In order to obtain v_0 , we need $v_B \min$.

Case #1 (no bottom)



We need finite N at all points between B and C.

(Consider B' any point between B & C)

$$\sum F_n = ma_n \\ N + mg \sin \theta = ma_{n2} \\ N + mg \sin \theta = m \frac{v_{B'}^2}{r}$$

$$v_{B'}^2 = \frac{rN}{m} + rg \sin \theta$$

Set #8

3. continued.

For minimum v_o , we need minimum v_B^2 .
For minimum v_B^2 , we need $N=0$ and $\theta = 90^\circ$.

$$v_B^2 = \frac{Nr}{m} + rg \sin 90^\circ$$

$$v_B^2 = rg \quad \textcircled{2}$$

Substituting $\textcircled{2}$ into $\textcircled{1}$,

$$v_o^2 = rg + 2gh$$

$$\underline{v_o = 7.98 \text{ m/s}}$$

Case #2 (with bottom)

We need finite velocity at B.

For minimum v_o , we need minimum v_B ($v_{B\min} = 0$).

$$v_o^2 = v_B^2 + 2gh$$

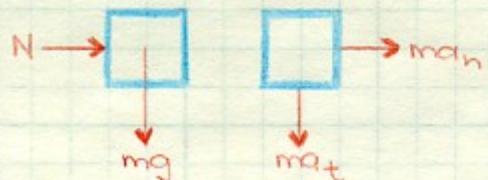
$$= 2gh$$

$$\underline{v_o = 7.67 \text{ m/s}}$$

Set #8

3. continued

(b) Force exerted on loop at C.



$$\sum F_n = man \\ N = m \frac{v_c^2}{r} \quad \textcircled{3}$$

We need v_c : $T_A + V_A = T_c + V_c$
 $\cancel{\frac{1}{2}mv_0^2} + 0 = \cancel{\frac{1}{2}mv_c^2} + mg \quad (2.5)$

$$v_c^2 = v_0^2 - 5g \quad \textcircled{4}$$

Case #1 (no bottom)

Substituting ① into ④

$$\begin{aligned} v_c^2 &= v_0^2 - 5g \\ &= (rg + 2gh) - 5g \\ &= rg + 2g(2.5) - 5g \\ v_c^2 &= rg \quad \textcircled{5} \end{aligned}$$

Now, we can solve for N (equation ③).
 Plug in ⑤.

$$\begin{aligned} N &= m \frac{v_c^2}{r} \\ &= \frac{m(1.5g)}{r} \\ \underline{\underline{N}} &= 5.89 \text{ N} \end{aligned}$$

Case #2 (with bottom)

Since v_B in ① is 0, $v_0^2 = 2gh$.
 Substituting into ④,

$$\begin{aligned} v_c^2 &= 2gh - 5g \\ &= 2(3)g - 5g \\ &= g \end{aligned}$$

$$\begin{aligned} N &= \frac{mg}{r} \\ &= \underline{\underline{3.92 \text{ N}}} \end{aligned}$$