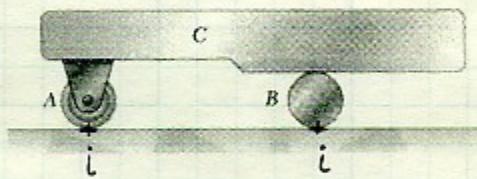


### Set #17 – Acceleration in Plane Motion

1. A carriage C is supported by a caster A and a cylinder B, each of 50-mm diameter. Knowing that at the instant shown the carriage has an acceleration of  $2.4 \text{ m/s}^2$  and a velocity of  $1.5 \text{ m/s}$ , both directed to the left, determine

- the angular accelerations of the caster and of the cylinder,
- the accelerations of the centers of the caster and of the cylinder.



Given:  $d_A = d_B = 50 \text{ mm}$

$$a_c = 2.4 \text{ m/s}^2 \quad \leftarrow$$

$$v_c = 1.5 \text{ m/s} \quad \leftarrow$$

Find: (a)  $\alpha_A, \alpha_B$   
 (b)  $\ddot{\alpha}_A, \ddot{\alpha}_B$

Solution:

For pin connections, the points have the same acceleration.  
 (Point A is in rectilinear motion.)

$$\rightarrow \ddot{\alpha}_A = 2.4 \text{ m/s}^2 \quad \leftarrow$$

$$\Delta x_A = \Delta \theta_A r$$

$$v_A = \omega_A r_{AL}$$

$$a_A = \alpha_A r_{AL}$$

$$\rightarrow \alpha_A = \frac{2.4 \text{ m/s}^2}{.025 \text{ m}}$$

$$\alpha_A = 96 \text{ rad/s}^2 \quad \curvearrowright$$

Point B is also in rectilinear motion.

$$\Delta x_B = \frac{1}{2} \Delta x_c \quad (\text{refer to following page})$$

$$v_B = \frac{1}{2} v_c$$

$$a_B = \frac{1}{2} a_c$$

$$\ddot{\alpha}_B = 1.2 \text{ m/s}^2 \quad \leftarrow$$

$$\Delta x_B = \Delta \theta r_{B/L}$$

$$v_B = \omega_B r_{BL}$$

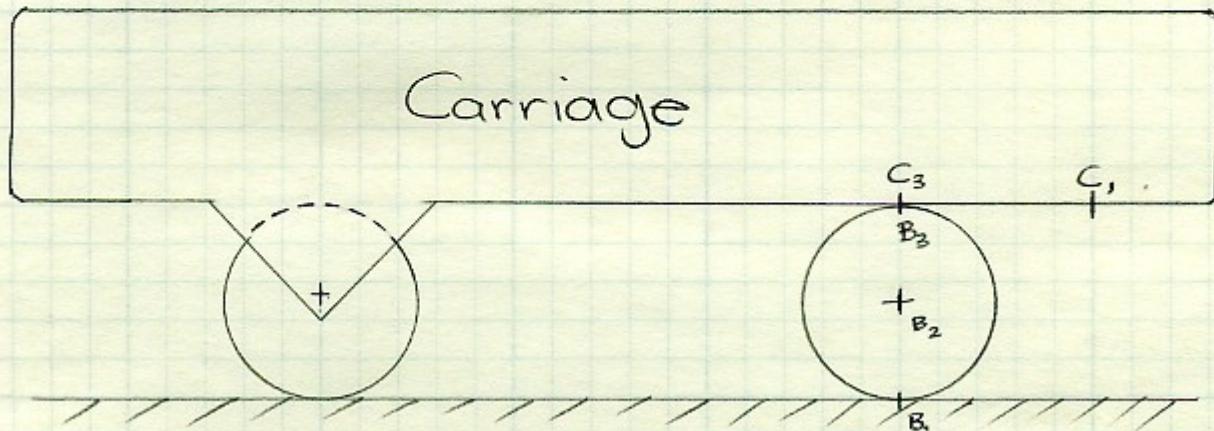
$$a_B = \alpha_B r_{BL}$$

$$\rightarrow \alpha_B = \frac{1.2 \text{ m/s}^2}{.025 \text{ m}}$$

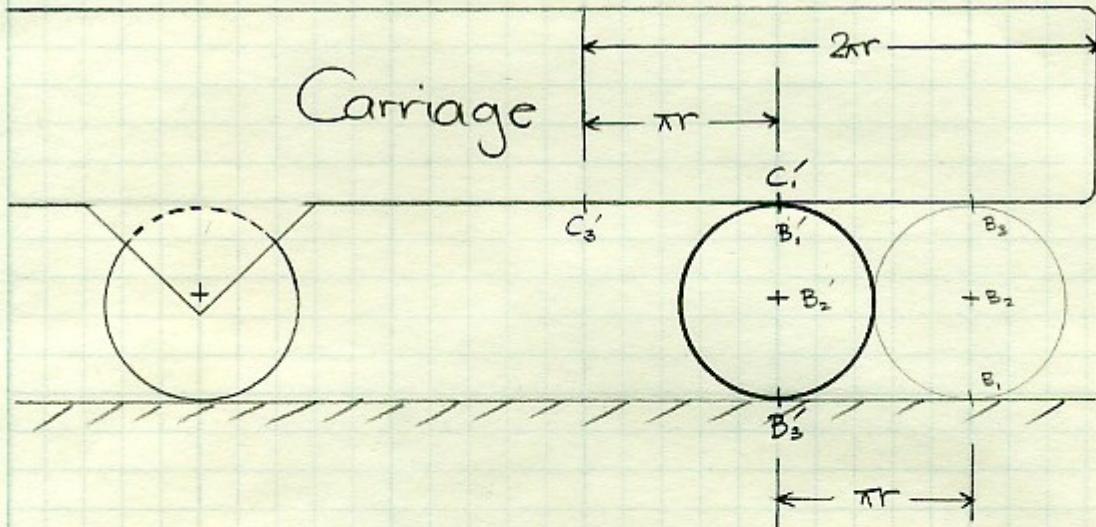
$$\alpha_B = 4.8 \text{ rad/s}^2 \quad \curvearrowright$$

Set #17

i. continued



After B rotates through  $\pi$



$$\Delta X_c = 2 \Delta X_B$$
$$V_c = 2 V_B$$

### Set #17 – Acceleration in Plane Motion

2. The motion of the 75-mm-radius cylinder is controlled by the cord shown. Knowing that end E of the cord has a velocity of 300 mm/s and an acceleration of 480 mm/s<sup>2</sup>, both directed upward, determine the acceleration

- a) of point A,
- b) of point B.

Given:  $r = 75 \text{ mm}$   
 $\vec{v}_E = 300 \frac{\text{mm}}{\text{s}}$  ↑  
 $\vec{a}_E = 480 \frac{\text{mm}}{\text{s}^2}$  ↑

Find: (a)  $\vec{a}_A$   
(b)  $\vec{a}_B$

Solution:

$$\vec{a}_A = \vec{a}_G + \vec{a}_{A/G} \\ = \vec{a}_G + [(\vec{\alpha} \times \vec{r}_{A/G}) + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{A/G})] \quad \text{---(1)}$$

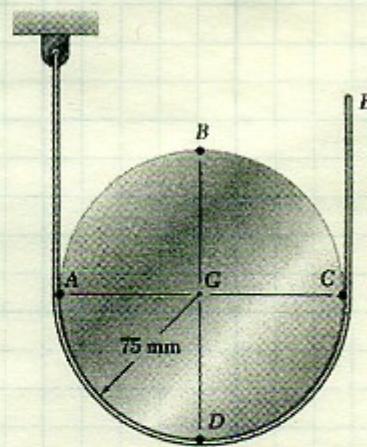
$$\vec{a}_B = \vec{a}_G + [(\vec{\alpha} \times \vec{r}_{B/G}) + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{B/G})] \quad \text{---(2)}$$

To solve for  $\vec{a}_A$  and  $\vec{a}_B$ , we need  $\vec{a}_G$ ,  $\alpha$ ,  $\omega$

G is in Rectilinear motion

$$\vec{a}_G: \quad \Delta x_G = \frac{1}{2} \Delta x_E \quad (\text{refer to following page}) \\ v_G = \frac{1}{2} v_E \\ a_G = \frac{1}{2} a_E \\ = 240 \frac{\text{mm}}{\text{s}^2} \uparrow$$

$$\alpha: \quad \Delta x_G = \frac{1}{2} \Delta x_E \\ \Delta \theta_G r = \frac{1}{2} \Delta x_E \\ \omega r = \frac{1}{2} v_E \\ \alpha r = \frac{1}{2} a_E \\ \alpha = \frac{1}{2} \frac{a_E}{r} \\ = 3.2 \frac{\text{rad}}{\text{s}^2}$$



Set #17

2. continued

w: we have 2 points on a rigid body.

$$\vec{V}_A = \vec{0}$$
$$\vec{V}_c = 300 \text{ mm/s} \uparrow$$

$$\begin{aligned}\vec{V}_c &= \vec{V}_A + \vec{V}_{C/A} \\ \vec{V}_c &= \vec{0} + \omega r_{C/A} \\ \rightarrow \omega &= \frac{\vec{V}_c}{r_{C/A}} \\ &= \frac{300 \text{ mm/s} \uparrow}{2(75 \text{ mm})} \\ &= 2 \text{ rad/s} \rightarrow\end{aligned}$$

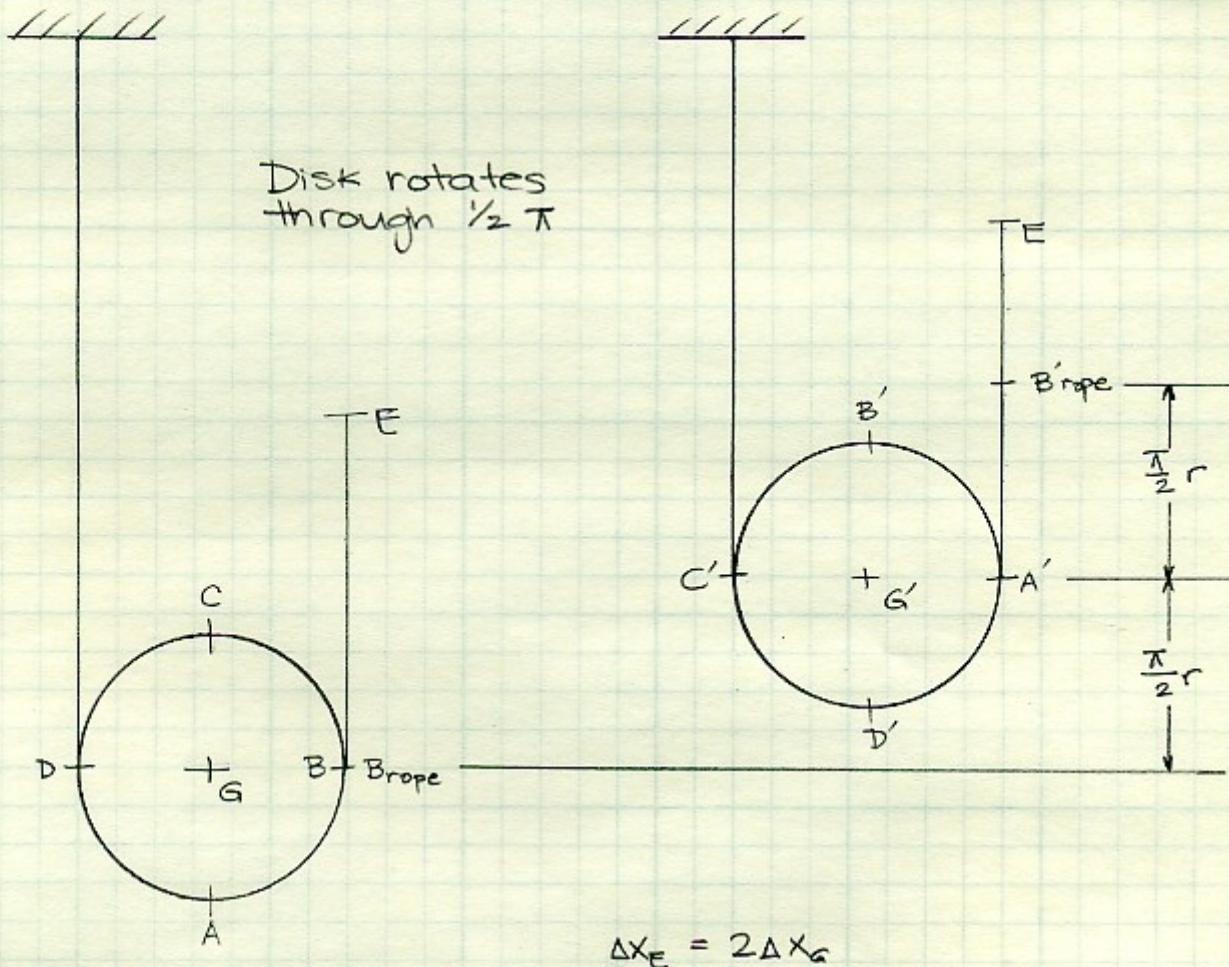
We can now use ① and ②

$$\begin{aligned}\vec{a}_A &= 240 \uparrow + (3.2)(75) \downarrow + 2^2 (75) \rightarrow \\ \vec{a}_A &= 240 \uparrow + 240 \downarrow + 300 \rightarrow \\ \underline{\vec{a}_A = 300 \text{ mm/s}^2 \rightarrow}\end{aligned}$$

$$\begin{aligned}\vec{a}_B &= 240 \uparrow + (3.2)(75) \leftarrow + 2^2 (75) \downarrow \\ \vec{a}_B &= 60 \downarrow + 240 \leftarrow \\ \underline{\vec{a}_B = 247 \text{ mm/s}^2 \rightarrow 14^\circ}\end{aligned}$$

Set #17

2. continued



$$\Delta x_E = 2\Delta x_G$$

$$v_E = 2v_G$$

$$\alpha_E = 2\alpha_G$$

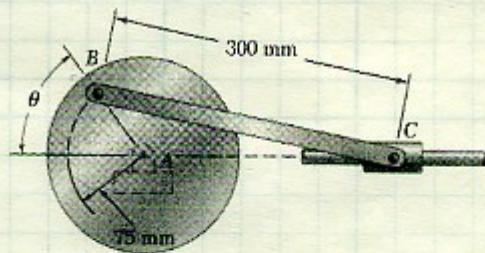
Alternatively,

$$x_G + \frac{1}{2}(2\pi r) + (x_G - x_E) =$$
$$\Delta x_G + \Delta x_G - \Delta x_E = 0$$
$$2\Delta x_G = \Delta x_E$$
$$2v_G = v_E$$
$$2\alpha_G = \alpha_E$$

### Set #17 – Acceleration in Plane Motion

3. The disk shown has a constant angular velocity of 360 rpm clockwise. Determine the acceleration of collar C when  $\theta = 90^\circ$ .

Given:  $\omega_{AB} = 360 \text{ rpm}$  (constant)  
 $= 37.7 \text{ rad/s}$   
 $\alpha_{AB} = 0$



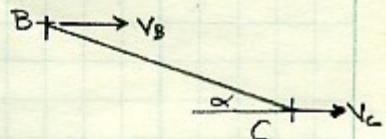
Find:  $\vec{a}_c$  when  $\theta = 90^\circ$

Solution:

$$\vec{a}_c = \vec{a}_B + \vec{a}_{C/B} \\ = \vec{a}_B + [\alpha_{BC} \times \vec{r}_{C/B} + \vec{\omega}_{CB} \times (\vec{\omega}_{CB} \times \vec{r}_{C/B})] \quad \text{---(1)}$$

$$\vec{a}_B : \quad \vec{a}_B = [(\alpha_{AB} \times \vec{r}_{B/A}) + (\vec{\omega}_{AB} \times (\omega_{AB} \times r_{B/A}))]$$
 $\vec{a}_B = \alpha r + \omega^2 r \downarrow$ 
 $\vec{a}_B = 0 + \omega^2 r \downarrow$ 
 $\vec{a}_B = (37.7 \text{ rad/s})^2 (75 \text{ mm}) \downarrow$ 
 $\vec{a}_B = 106.6 \text{ mm/s}^2 \downarrow$

$$\omega_{CB} : \quad \vec{v}_B = \vec{\omega}_{AB} \times \vec{r}_{B/A}$$
 $\vec{v}_B = (37.7 \text{ rad/s}) (75 \text{ mm}) \rightarrow$ 
 $\vec{v}_B = 2.83 \text{ mm/s} \rightarrow$ 
 $\vec{v}_c = \vec{v}_B + \vec{\omega}_{BC} \times \vec{r}_{C/B}$



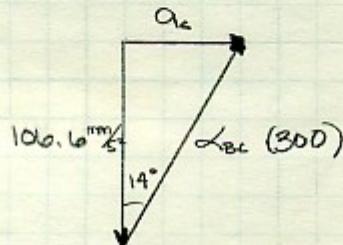
NOTE: This can't work if  $\omega_{BC} \neq 0$ .

Therefore,  $\omega_{BC} = 0$ !

→ BC is in translation at this instant.

Using ①,

$$\vec{a}_c = 106.6 \downarrow + \alpha_{BC} r_{C/B} \nearrow 14^\circ + 0 \\ = 106.6 \downarrow + \alpha_{BC} (300) \nearrow 14^\circ$$



$$\frac{\vec{a}_c}{a_c} = 106.6 \tan 14^\circ \\ \underline{\underline{\frac{a_c}{a_c} = 27.5 \text{ mm/s}^2 \rightarrow}}$$